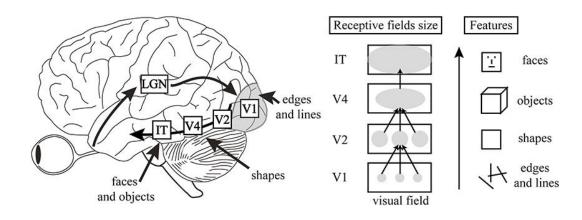
# THEORY OF MACHINE LEARNING

**LECTURE 18** 

NEURAL NETWORKS - REPRESENTATION BASICS

#### RECAP

- Perceptron, or linear threshold
  - Hypotheses of form  $sign(\langle a, x \rangle)$  for an appropriate weight vector a
  - Generally,  $\sigma(a^Tx)$  for some "activation function"  $\sigma$
- Biologically inspired, arithmetic circuit (with threshold gate)
- Idea behind neural nets:
  - Perceptrons detect "basic" or "primitive" features; 'composing' them allows for complex decision-making
  - Supported by human visual system (V1, V2, ...)



# RECAP: ARTIFICIAL/DEEP NEURAL NETWORK (DNN)

**Definition.** A layered "circuit" that takes a vector of input features x, produces output  $y = F_r \circ F_{r-1} \circ \cdots \circ F_1(x)$ , where each  $F_i$  is a function of the form  $F_i(z) = \sigma(Az + b)$ , for some activation function  $\sigma()$  (that acts coordinate-wise)

- Common activation functions:
  - Threshold
  - Sigmoid: (continuous approx.)  $\frac{1}{1+e^{-x}}$
  - ReLU, Tanh
  - **...**

### **BASICS**

- Neural networks are basically a (fairly complex) hypothesis class takes input x, produces y
- Question (vanilla supervised learning): given data  $(x_1, y_1), (x_2, y_2), ...$  from some distribution D, find h in this class that minimizes the risk

ERM problem usually called neural network "training" - given data, find best hypothesis  $(f(x_i) = y_i)$  for all i

### THEORY OF DEEP LEARNING

- Expressibility
  - What kinds of functions can be obtained using a DNN?
- Training complexity & training dynamics for GD and variants
  - Can the ERM problem be solved efficiently? What guarantees are possible?
- Generalization
  - What kind of generalization bounds can we prove? (VC dimension?)

**Key:** "easy" answers for all questions, but unsatisfactory for realistic settings

#### **EXPRESSIBILITY BASICS**

- Barron's theorem [93]. Any continuous function f that satisfies an appropriate "niceness" condition (parametrized by C) can be approximated to error  $\epsilon$  (in L2!) by a 2-layer NN with  $\sim \frac{C^2}{\epsilon}$  internal nodes
- (Nice functions can be approximated by small NNs)
- Universal approximation [Cybenko, Hornik '87,'91]. Any continuous function (over a compact domain) can be approximated by a 2-layer NN with any non-linearity (not a polynomial)

But wait.. who uses infinitely wide 2 layer nets?

#### **DEPTH VERSUS WIDTH**

- Practical intuition:
  - Depth allows "meaningful features" while width is for "brute force memorization"
- Universality results degrade rapidly with dimensions
  - Curse of dimensionality
  - Modern nets work with high dimensional data
- Does higher depth lead to higher expressibility (with much fewer neurons)?
- Bunch of works ... [Eldan and Shamir (depth 2 vs depth 3)], [Telgarsky],
  2015-16

#### **POWER OF DEPTH**

**Theorem template**. There exists a network of depth D and "size" S that computes some function f that cannot be approximated by the output of any network with depth d and size S' (typically if d << D, S' will be >> S)

- "Depth versus width" results
- Reminiscent of circuit complexity (original work of Minsky, Pappert)

[Telgarsky 16]. For any k>0, theorem holds with:

 $D = S \sim k^3$ , d = k, and  $S' = 2^k$  (and ReLU activations)

## **PROOF OUTLINE**

- Consider just one-dimensional inputs and ReLU activations
- Key insight:
  - depth D lets us achieve exp(D) many "osciallations" in f
  - getting so many osciallations with depth d requires huge width!