

Advanced Algorithms

Lecture 24: Complexity: limits on efficient computation

Announcements

- HW 5 due tomorrow (HW 6 will be released tomorrow.)
- Problem 3 clarification (purely experiment) .
- HW 6 logistics (4-day grace period) .
↓
(Dec 4-6 → Wednesday) .

Last two weeks

Instance of problem



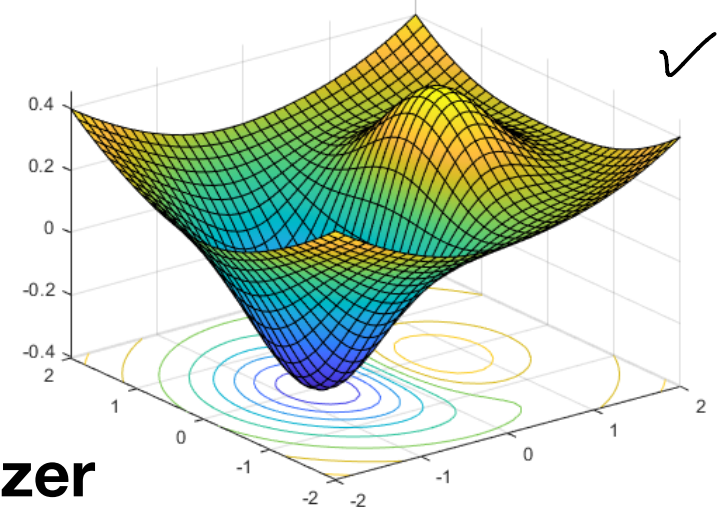
Optimization formulation

variables x_1, x_2, \dots
constraints
objective

“relaxation”

Solution to problem instance
“rounding”

opt solution:
 $x_1 = 0, x_2 = 1, \dots$



Optimizer

Optimization formulations

Continuous approaches for discrete problems

- Can sometimes lead to polynomial time algorithms (weighted matching)
- Often used to obtain “approximation algorithms”
- Integrality gap



Lower bounds

- Can we search for an element x in a sorted, n -element array in time $< \log n$?
- Can we solve the shortest path problem in time $O(m+n)$ on all graphs?
- Can we multiply two $n \times n$ matrices in time $O(n^2)$?
- Can we factor an n digit number in $\text{poly}(n)$ time?

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Challenge in lower bounds: must reason about an algorithm without knowing what it is!

Computational model

Problem. can we search for an element x in a sorted, n -element array in time $< \log_2 n$?

$A[1], A[2], \dots, A[n]$.

- What operations are “allowed”? \rightarrow .. Comparing gives an advantage ..
- What about randomness?

\rightarrow may / may not help.

A formal lower bound

Problem. can we search for an element x in a sorted, n -element array in time $< \log n$?

- What operations are “allowed”?
- What about randomness?

queries are of the form:
is $x < A[i]$?

Theorem. consider any deterministic algorithm for “search” problem that can only access array via comparisons. Then algorithm must take at least $\log_2 n$ steps (comparisons).

↓
(we don't know what the algorithm is!) .

A formal lower bound

ALG:

query 1: $x < A[i] ?$

query 2:

\vdots

query l: $x \leq \dots$

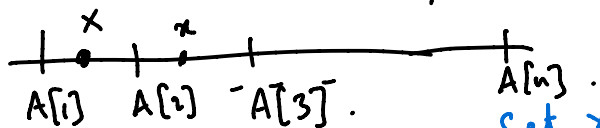


needs to output
index of x in the
array.



what if algorithm needs
to output only YES/NO
(element x \notin array or
not.).

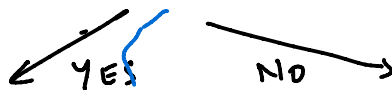
$A[1], \dots, A[n]$. # to find = x .



Set $x = A[j]$

query 1:

$x < A[i]?$



query 2:

$x < A[i']?$

$x < A[i'']?$



⋮

query l . $x < A[...]$?

index...

⋮

index = j

Obsn: Any deterministic alg is characterized by this "decision tree".

Claim: if algorithm is always correct, then # of leaves $\geq n$.

$$\Rightarrow 2^l \geq n \Rightarrow l \geq \log_2 n$$

Lower bounds



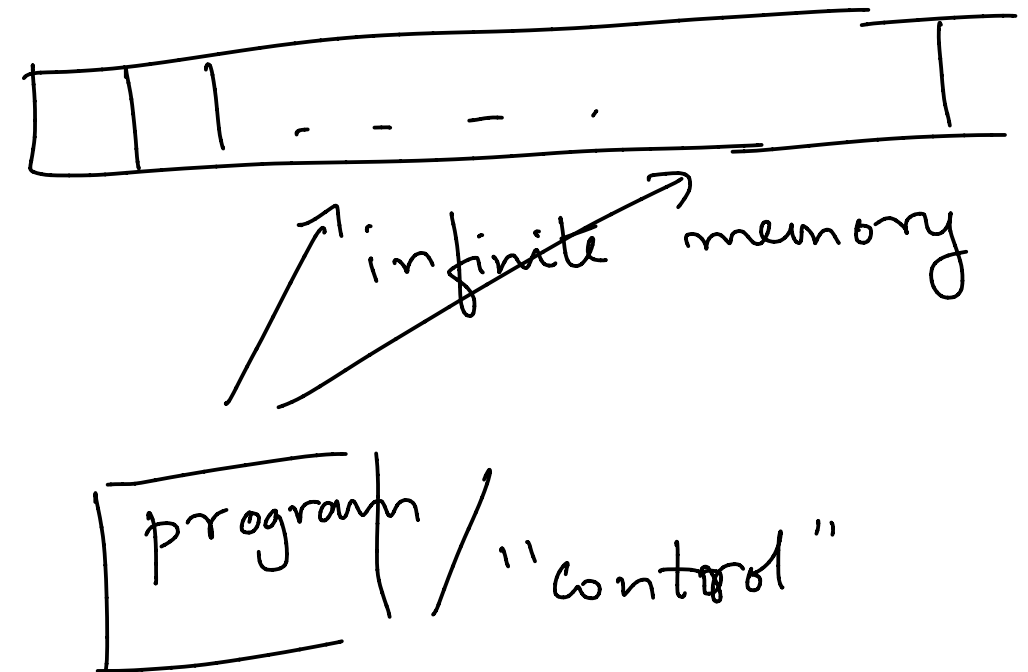
- Lower bounds for “limited” models very useful in algorithm design
- **Key question:** is there a model that captures “all computations”

Candidate: There is no poly time algorithm for factorization.

Claim:

Universal models

- Turing machine
- Equiv., RAM model



... Quantum computers--

↑

Church-Turing “thesis”. any *reasonable* physical model of computation can be simulated “efficiently” (polynomial slowdown) on a Turing machine

Universal models

- Turing machine
- Equiv., RAM model

Church-Turing “thesis”. any *reasonable* physical model of computation can be simulated “efficiently” (polynomial slowdown) on a Turing machine

Assuming it's true, need to only show lower bounds on a Turing machine



Reasoning about problems

[Can a # be factored efficiently?
Can we solve maximum ind. set
in poly time?]

- “Simplification”: move to **decision version**
 - ★ • Does graph have an independent set of size k ?
 - Does graph have a path of length $\leq L$ between u and v ?
- problems where answer is YES/NO.

Max-independent set:



set of vertices without any edges between them. — find the largest

Decision vs optimization

Theorem. suppose we can solve the decision version of the independent set problem in poly time, we can actually solve max-IS in poly time

(useful because LOWER BOUNDS for decision problem
↕
Lower bounds for optimization version).

Decision vs optimization

Proof: — first find k , the size of max indep. set.

— ~~for~~ pick any vertex u & consider $G \setminus u$

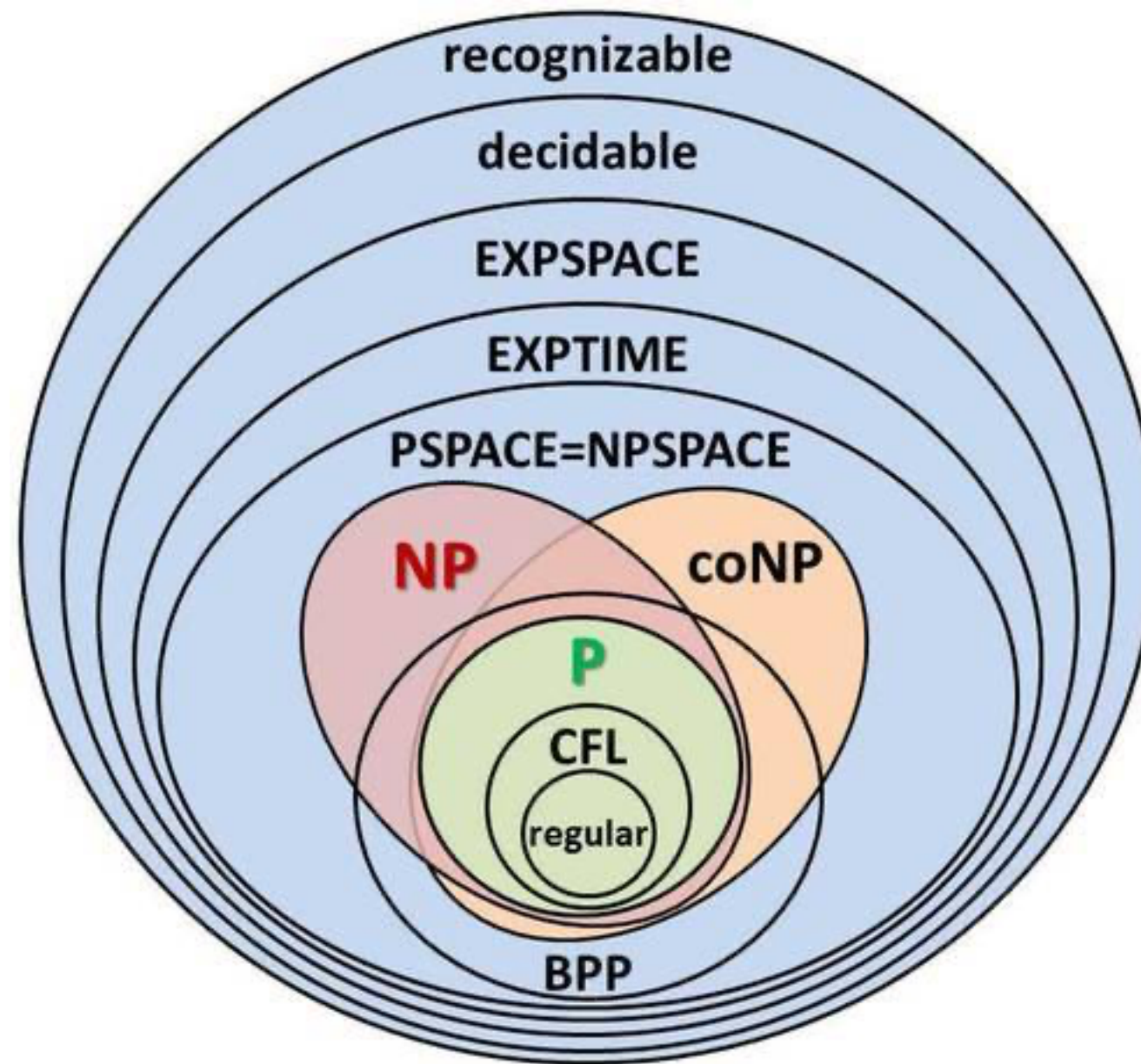
— if $G \setminus u$ has indep set of size $\geq k$, then
recurse into $G \setminus u$.

— if not, add u to the IS and recurse into
 $G \setminus u$.

Complexity

Question. does the decision version of IS have a polynomial time algorithm?

Complexity “classes”



The class P

The class NP

Question. does the graph G have an independent set of size k ?

The class NP

Most “puzzles” belong to NP

Boolean satisfiability

“Captures” the essence of NP