

Lecture 17

Context Bounding Checkers

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Huge Number of Thread Schedules

- ▶ Concurrent program with n threads where each thread has k instructions has

$$(n * k)! / (k!)^n \geq (n!)^k$$

interleavings

- ▶ Exponential in both n and k !
- ▶ Example: 5 threads with 5 instruction each

$$\begin{aligned} 25! / 5!^5 &= 6.2336074e+14 \\ &= 623 \text{ trillion interleavings} \end{aligned}$$

Java Path Finder (JPF)

- ▶ Program checker for Java
- ▶ Properties to be verified
 - ▶ Program assertions
 - ▶ LTL properties
- ▶ Depth-first and breadth-first search, heuristics
 - ▶ Uses static analysis techniques to improve the efficiency of the search
- ▶ Requires a complete Java program
 - ▶ Cannot handle native code

Combating State Space Explosion

- ▶ Symmetry reduction
 - ▶ Search equivalent states only once
- ▶ Partial order reduction
 - ▶ Do not search thread interleavings that generate equivalent behavior
- ▶ Static analyses
 - ▶ Reduce state space using static analyses
- ▶ User-provided restrictions
 - ▶ Manually bound variable domains, array sizes,...

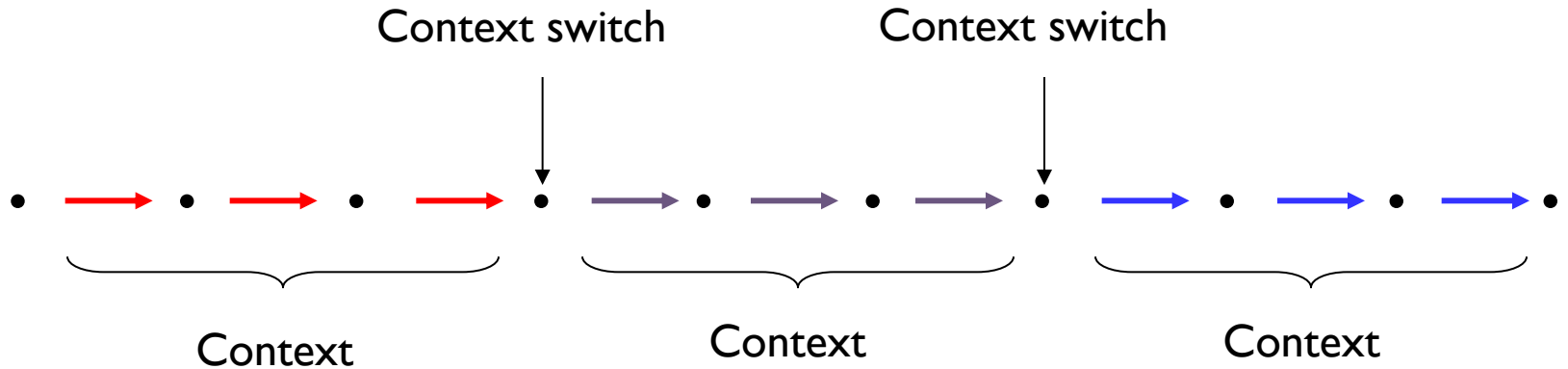
This Time

- ▶ Context-bounded verification of concurrent programs
- ▶ Sequentialization of concurrent programs

Context-Bounded Verification

slides acknowledgements: Shaz Qadeer, Madan Musuvathi

Context-Bounded Verification



- ▶ Many subtle concurrency errors are manifested in executions with few context switches
- ▶ Analyze all executions with few context switches

Context-Bounded Reachability Problem

- ▶ An execution is c -bounded if every thread has at most c contexts
- ▶ Does there exist a c -bounded execution from a state S to a state E ?

CB Reachability is NP-Complete

► Membership in NP

- Witness is an initial state and $n \cdot c$ sequences each of length at most $|L \times G|$

n = # of threads, c = # of contexts

L = # of program locations, G = # of global states

► NP-hardness

- Reduction from the CIRCUIT-SAT problem

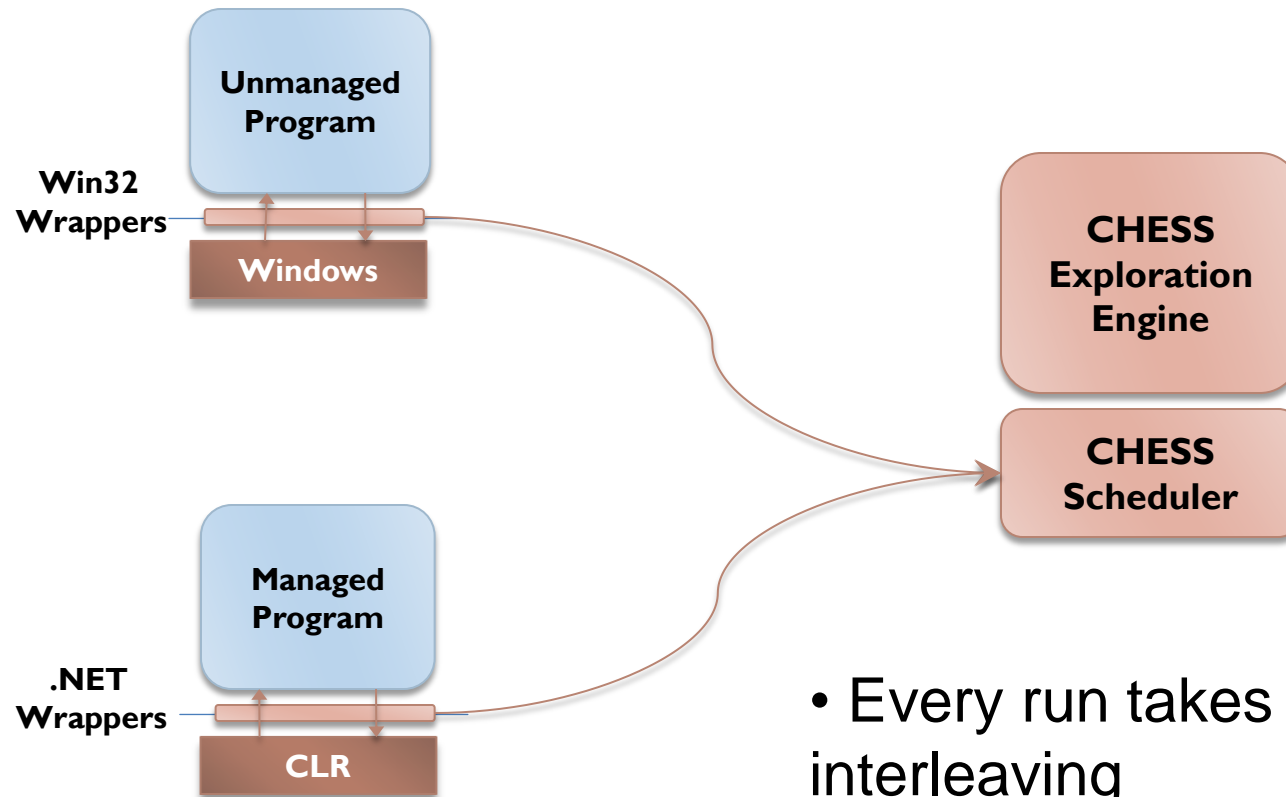
Complexity of Safety Verification

	Unbounded	Context-bounded
Finite-state systems	PSPACE complete	NP-complete
Pushdown systems	Undecidable	NP-complete

CHESS: Systematic Testing for Concurrency

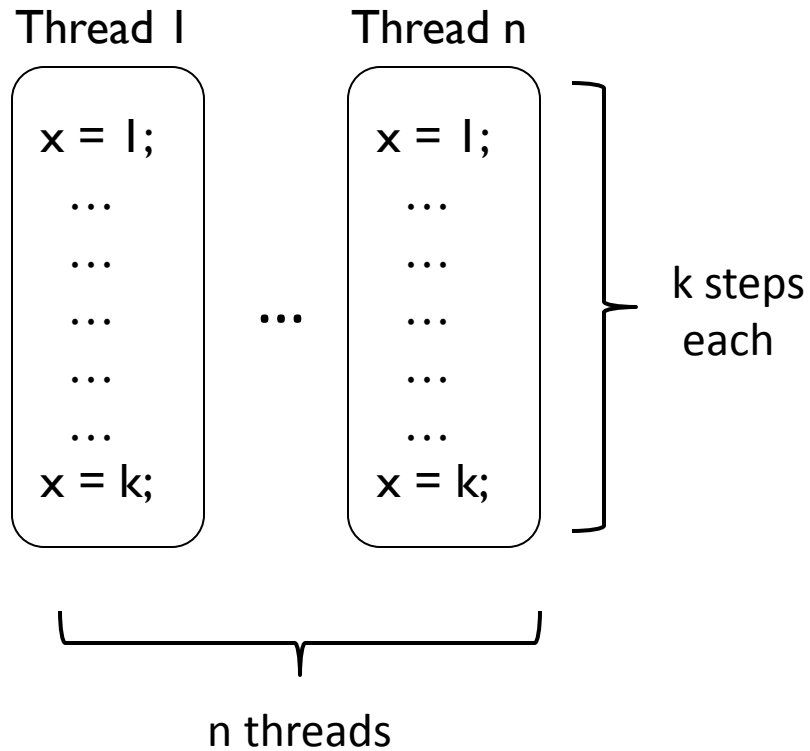
- ▶ CHESS is a user-mode scheduler
- ▶ Controls all scheduling nondeterminism
 - ▶ Replace the OS scheduler
- ▶ Guarantees:
 - ▶ Every program run takes a different thread interleaving
 - ▶ Reproduce the interleaving for every run

CHESS Architecture



- Every run takes a different interleaving
- Reproduce the interleaving for every run

State-Space Explosion

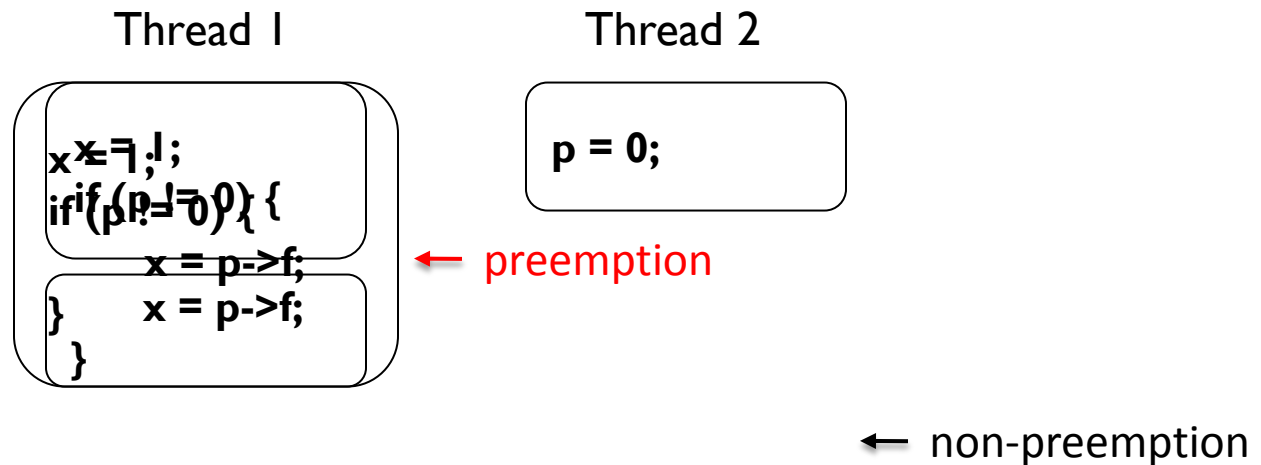


- ▶ Number of executions is $O(n^{nk})$
- ▶ Exponential in both n and k
 - ▶ Typically: $n < 10$, $k > 1000$
- ▶ Limits scalability to large programs

Goal: Scale CHESS to large programs (large k)

Preemption-Bounding

- ▶ Prioritize executions with small # of preemptions
- ▶ Two kinds of context switches:
 - ▶ Preemptions – forced by the scheduler
 - ▶ E.g., time-slice expiration
 - ▶ Non-preemptions – a thread voluntarily yields
 - ▶ E.g., blocking on an unavailable lock, thread end

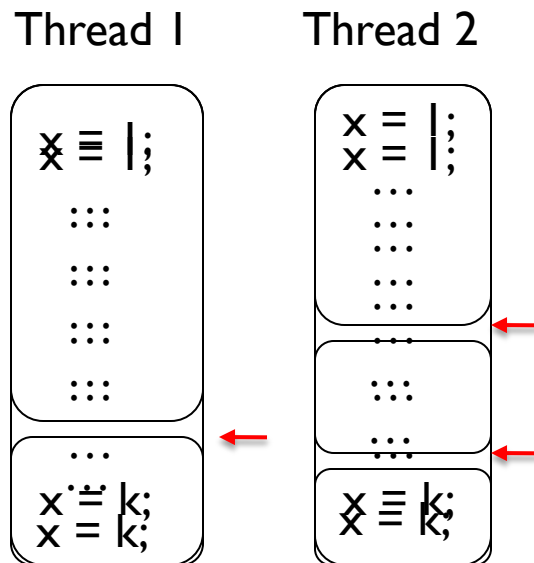


Preemption-Bounding in CHESS

- ▶ The scheduler has a budget of c preemptions
 - ▶ Nondeterministically choose the preemption points
- ▶ Resort to non-preemptive scheduling after c preemptions
- ▶ Once all executions explored with c preemptions
 - ▶ Try with $c+1$ preemptions

Property 1: Polynomial Bound

- ▶ Terminating program with fixed inputs and deterministic threads
 - ▶ n threads, k steps each, c preemptions
- ▶ Number of executions $\leq {}_{nk}C_c * (n+c)!$
 $= O((n^2k)^c * n!)$
- ▶ Exponential in n and c , but not in k !



- Choose c preemption points
- Permute $n+c$ atomic blocks

Property 2: Simple Error Traces

- ▶ Finds smallest number of preemptions to the error
- ▶ Number of preemptions better metric of error complexity than execution length

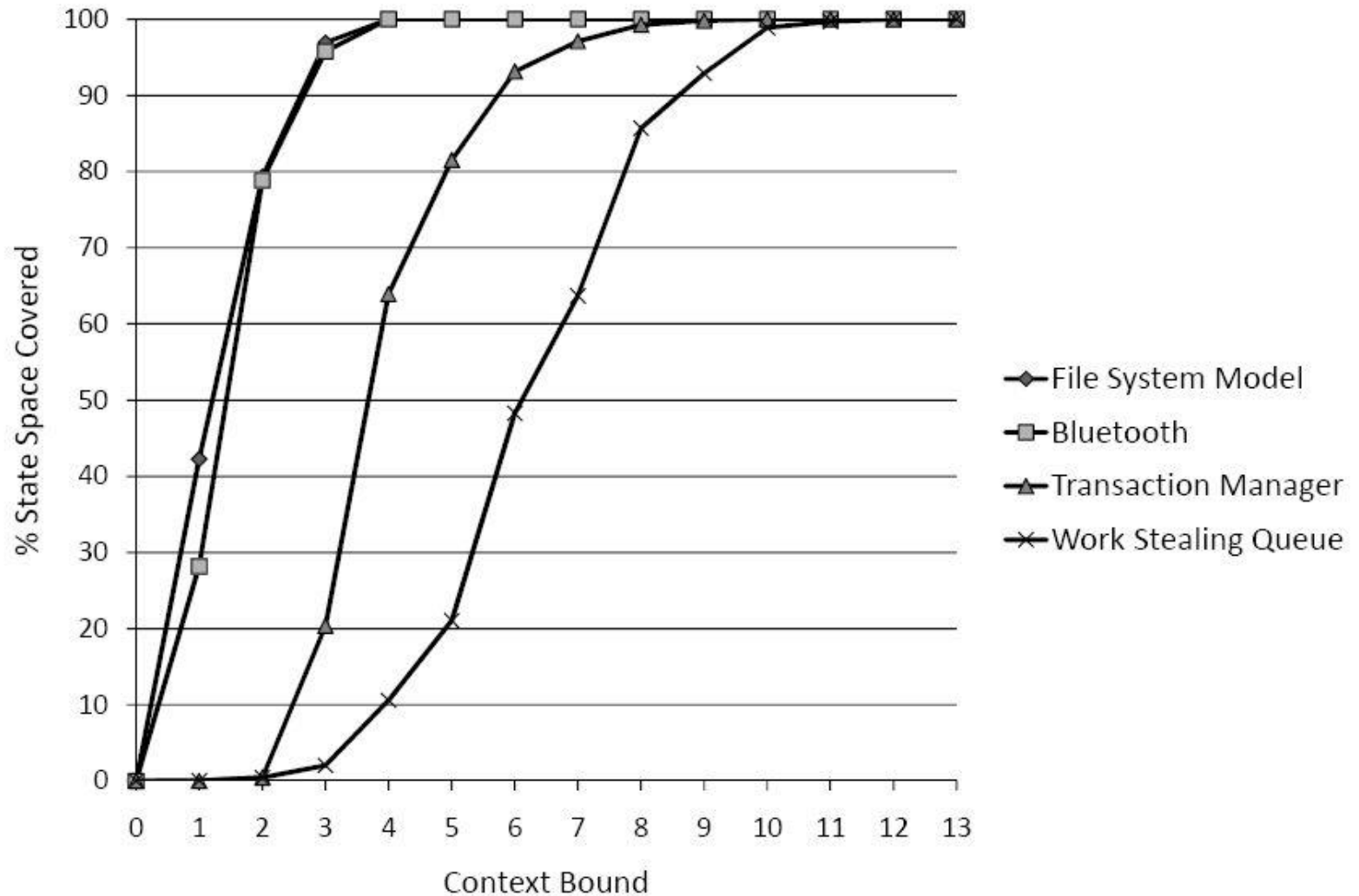
Property 3: Coverage Metric

- ▶ If search terminates with preemption-bound of c , then any remaining error must require at least $c+1$ preemptions
- ▶ Intuitive estimate for
 - ▶ The complexity of the bugs remaining in the program
 - ▶ The chance of their occurrence in practice

Property 4: Many Bugs with Few Preemptions

Program	kLOC	Threads	Preemptions	Bugs
Work-Stealing Queue	1.3	3	2	3
CDS	6.2	3	2	1
CCR	9.3	3	2	2
ConcRT	16.5	4	3	4
Dryad	18.1	25	2	7
APE	18.9	4	2	4
STM	20.2	2	2	2
PLINQ	23.8	8	2	1
TPL	24.1	8	2	9

Coverage vs Preemption-Bound





Sequentialization of Concurrent Programs

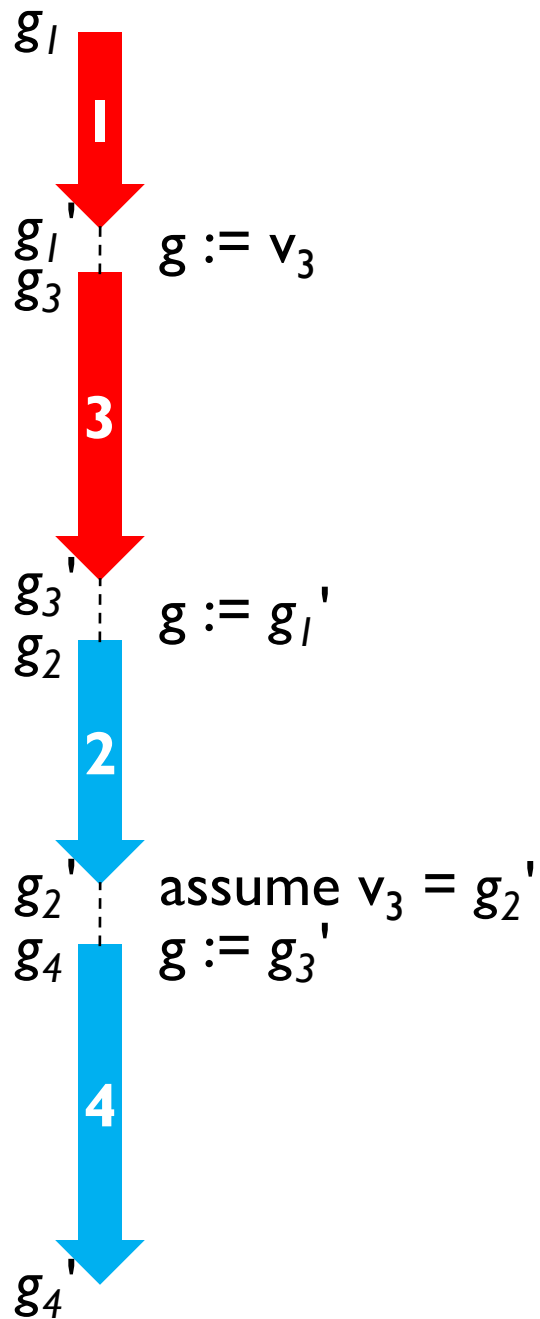
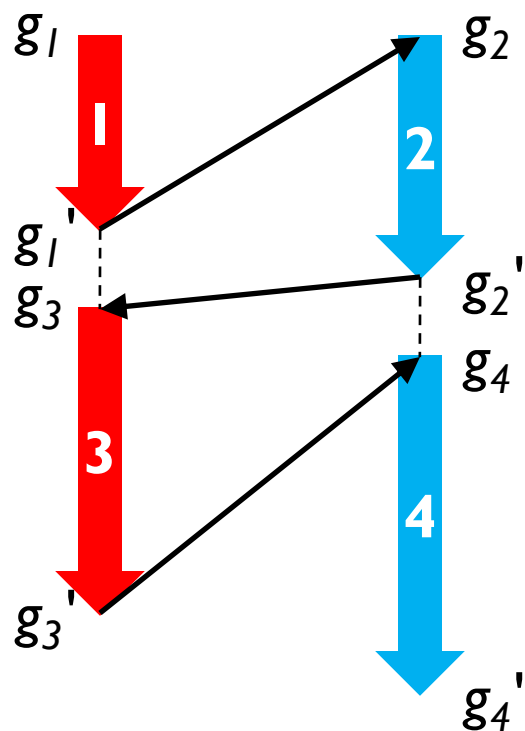
Concurrent Using Sequential

- ▶ Transform context bounded analysis of concurrent programs into analysis of sequential programs
- ▶ KISS [Qadeer, Wu, PLDI '04]
 - ▶ Only up to 2 context switches
- ▶ [Lal, Reps, CAV '08], [La Torre, Madhusudan, Parlato, CAV '09]
 - ▶ More general transformations, N context switches
 - ▶ Applied only on small, manually constructed Boolean programs

Simple Translation Example

- ▶ Translation of one concurrent trace
- ▶ Two threads: Thread₁, Thread₂
- ▶ One shared variable: g
- ▶ 3 context switches, 4 execution segments (or contexts)
- ▶ Main idea [Lal, Reps, CAV '08]
 - ▶ Avoid storing local state
 - ▶ Introduce unconstrained symbolic “prophecy” values instead of still unavailable “future” values
 - ▶ Constrain them when “future” values become available

Thread₁ Thread₂



Lal-Reps Translation

- N contexts per thread, shared variable g

$T_1 \parallel T_2$

assert F

```
int g1, g2, ..., gN, v2, ..., vN;
int k := 1;
assume (g2 = v2 && g3 = v3 ... gN = vN);
```

```
st → switch(k):
  case 1: Schedule; st[g1/g];
  case 2: Schedule; st[g2/g];
  ...
```

INIT;

$L_1: T_1^s;$

$L_2: T_2^s;$

$L_3: \text{END};$

assert F

```
assume (g1 = v2 && g2 = v3 ...);
```

Schedule

```
if (k <= N) {if (*) k++;}
else {k := 1; goto Li+1};
```

Field Abstraction Example

- Fields = $\{f, g\}$
- Tracked fields = $\{f\}$

► Before

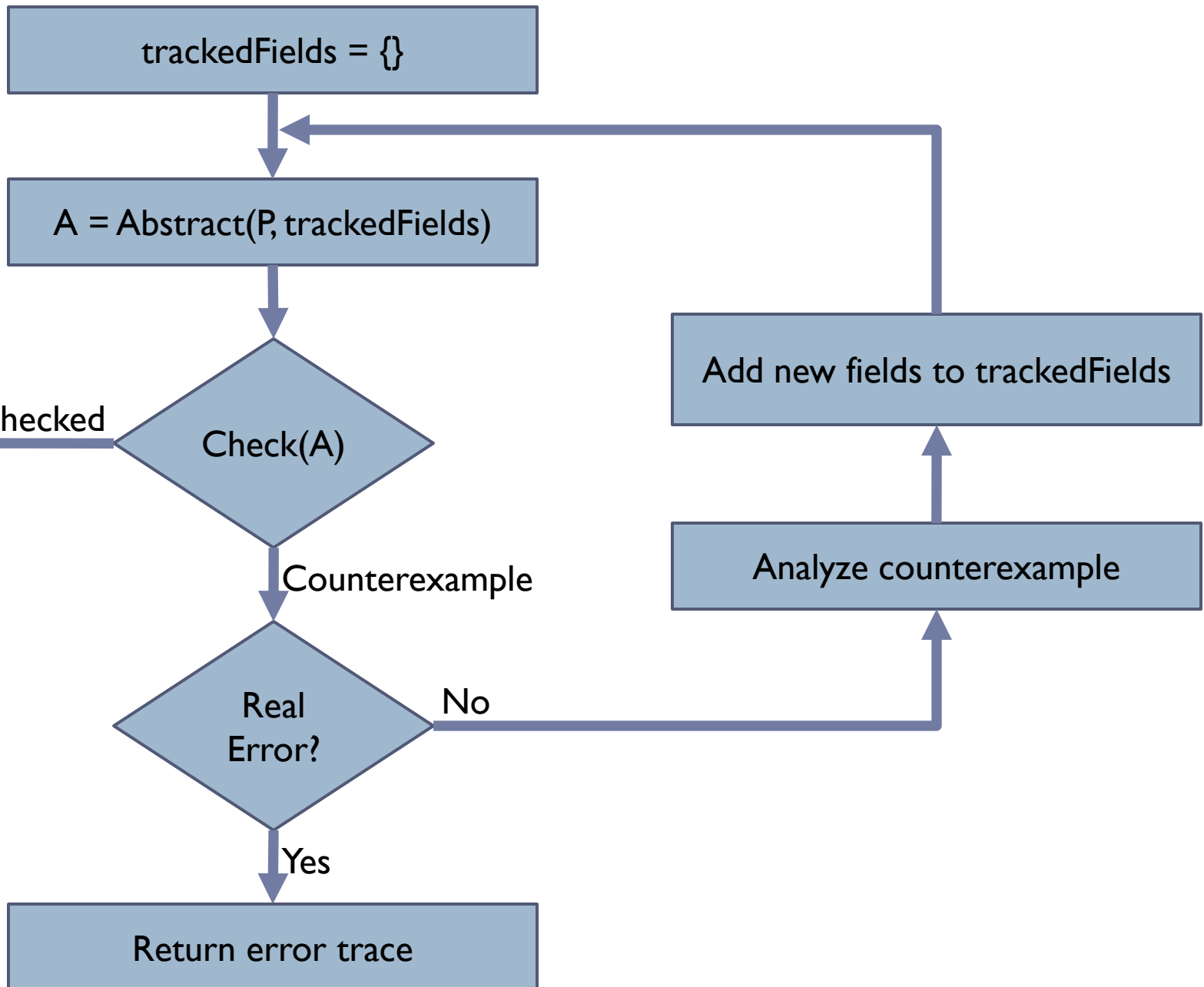
```
tmp = x->f;  
tmp = x->g;  
y->g = tmp;
```

□ Abstraction...

```
tmp = x->f;  
tmp = nondet();  
y->g = tmp;
```

Field Abstraction CEGAR

- ▶ How to discover tracked fields automatically?
- ▶ Algorithm based on CounterExample Guided Abstraction Refinement (CEGAR) framework



Experimental Results

- ▶ Prototype implementation: STORM
- ▶ 4 Windows Device Drivers
- ▶ Harness
 - ▶ Creates driver request that gets processed concurrently by multiple routines
 - ▶ Dispatch | Cancellation
 - ▶ Dispatch | Cancellation | Completion
 - ▶ Dispatch | Cancellation | Completion | DPC
- ▶ Checked property
 - ▶ Driver request cannot be used after it has been completed (i.e. use after free)

Varying Number of Contexts N

► Manually provided tracked fields

Driver	kLOC	#T	Routine	1	2	3	4	5
usbsamp Bug found!	4	3	read	17.9	37.7	65.8	66.8	85.2
			write	17.8	48.8	52.3	74.3	109.7
			ioctl	4.4	5.0	5.1	5.3	5.4
usbsamp_fix	4	3	read	16.9	28.2	38.6	46.7	47.5
			write	18.1	32.2	46.9	52.5	63.6
			ioctl	4.8	4.7	5.1	5.1	5.2
mqueue	14	4	read	62.1	161.5	236.2	173.0	212.4
			write	48.6	113.4	171.2	177.4	192.3
			ioctl	120.6	198.6	204.7	176.1	199.9
daytona	22	2	ioctl	3.4	3.8	4.2	4.5	5.6
serial	32	3	read	36.5	95.4	103.4	240.5	281.4
			write	37.3	164.3	100.8	233.0	649.8

Field Abstraction CEGAR

► N=2


Driver	Routine	#Fields Total	#TFieds Manual	#TFields CEGAR	#CEGAR Iterations	Time (s)
daytona	ioctl	53	3	3	3	244.3
mqueue	read	72	7	9	9	3446.3
	write			8	8	3010.0
	ioctl			9	9	3635.6
usbsamp_fix	read	113	1	3	3	4382.4
	write			4	4	2079.2
	ioctl			0	0	21.7
serial	read	214	5	5	5	3013.7
	write			4	3	1729.4

Bug Found (usbsamp)




- ▶ Sample driver in WinDDK
 - ▶ Example of how to write device drivers
 - ▶ Copy-pasted by driver vendors
 - ▶ Checked using existing tools
 - ▶ Bug confirmed and fixed
 - ▶ Requires 3 context switches
 - ▶ SLAM (SDV) – checks sequential code
 - ▶ KISS – only up to 2 context switches
- Bug could not be found by other tools

Bug Found

Thread₁
Dispatch Routine

 ReadRoutine(req) {
 ...
 WdfRequestMarkCancelable(
 req, CancelRoutine);
 ...
 WdfRequestComplete(req);
 ...
}

Thread₂
Cancellation Routine

 CancelRoutine(req) {
 assume (CancelRoutineSet
 && !reqCompleted);
 ...
  GetRequestContext(req); 
 ...
}